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## Existence of **D** vectorial Absolute

## EXISTENCE OF 1D VECTORIAL ABSOLUTE MINIMISERS IN L <sup>1</sup> UNDER MINIMAL ASSUMPTIONS

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Abstract. We prove the existence of vectorial Absolute Minimisers in the sense of Aronsson to the supremal functional  $E_1$  (u;  $\theta$ ) = kL (; u; Du

case of maps:  $R^n$  !  $R^N$ ) together with its associated system of equations begun in the early 2010s by the second author in a series of papers, see  $[K1]$ - $[K6]$ , [K8]-[K12

Theorem 1 generalises two respective results in the both the papers [BJW1] and  $[K9]$ . On the one handin  $[BJW1]$  Theorem 1 was established under the extra assumption  $C_2 = C_3 = 0$  which forces L  $(x; ; 0) = 0$  for all  $(x; ) 2 R R$ <sup>N</sup>. Unfortunately this requirement is incompatible with important applications of (1.1) to problems o $E^1$  -modelling of variational Data Assimilation  $\phi$ Var) arising in the Earth Sciences and especially in Meteorology (see [B, BS, K9]). An explicit model ofL is given by

(1.7) 
$$
L(x; ; P) := k(x) K( )^{2} + P V(x; )^{2};
$$

and describes the \error" in the following sense: consider the problem of nding

spaces $W^{1;qm}_{b}$  (;R<sup>N</sup>) such that, for any s  $-1$ , u<sup>m</sup>  $\rightarrow$  u<sup>-1</sup> weakly asm ! 1 in  $W^{1,s}$ (; R<sup>N</sup>) along a subsequence. Moreover,

(2.2) 
$$
E_1(u^1; ) = C_1 = \lim_{m \downarrow 1} C_m
$$
:

By approximate minimiser we mean thatu<sup>m</sup> satis es

(2.3) 
$$
E_m(u^m; )
$$
  $C_m < 2^{m^2}$ :

Finally, for any A measurable of positive measure the following lower semicontinuity inequality holds

(2.4) 
$$
E_1(u^1; A)
$$
  $\lim_{m \downarrow 1} \inf$ 

as m ! 1 along a subsequence. Now, recalling that  $v = u^m$  at the endpoints f Q 1g, and sinceu<sup>m</sup> is an approximate minimiser of (2.1) ov $M_b^{1;m}$  (; R<sup>N</sup>) for each m 2 N, by utilising minimality, the additivity of the integral and Holder inequality, we get

$$
E_m u^m
$$
; (Q, 1)  $E_m$  <sup>m</sup>; (Q, 1) + 2  $m^2$ 

and hence

(2.6) 
$$
E_m u^m
$$
; (0, 1)  $\frac{1}{m}$   $E_m$   $m$ ; (0, 1)  $\frac{1}{m}$  + 2  $m$   
 $E_1$   $m$ ; (0, 1) + 2  $m$ :

On the other hand, we have

$$
E_1 \quad m; \, ; (Q, 1) = max \quad E_1 \quad m; \, ; (Q, ) ;
$$
\n
$$
E_1 \quad m; \, ; (1, 1) ;
$$
\n
$$
E_1 \quad m; \, ; (1, 1) ;
$$

and since  $m_i = 1$  on (; 1), we have

$$
E_1 \quad m; \; ; (0,1) \quad \text{max} \; E_1 \quad m; \; ; (0, \; ) \; ; E_1 \quad 1; (0,1) \; ;
$$
\n
$$
= m; \; (1, \; 1)
$$

$$
E_1 \quad \stackrel{m;}{\ldots} ; (1 \quad ; 1) \quad :
$$

Combining (2.5)-(2.7) and (2.4), we get  $E_1$  u<sup>1</sup>; (0, 1) liminf max n  $E_1$  <sup>m;</sup> ; (Q ) ;  $E_1$  <sup>1</sup> ; (Q 1) ;  $E_1$  <sup>m;</sup> ; (1 ; 1) o max  $E_1$   $^{-1}$ ; (Q, 1);  $E_1$   $^{-1}$ ; ; (Q, ); n  $E_1$  <sup>1;</sup>;(1;1) o : (2.8)

Let us now denote the di erence quotient of a function! R<sup>N</sup> as  $D^{1;t}v(x)$  :=  $\frac{1}{t}[v(x + t)$  v(x)]. Then, we may write

D <sup>1</sup> ; (x) = D 1; <sup>1</sup> (0), x 2 (0; ); D <sup>1</sup> ; (x) = D 1; <sup>1</sup> (1), x 2 (1 ; 1),

Note now that 8

(2.9) 
$$
\sum_{y=1}^{6} E_1
$$
  $\sum_{y=1}^{1}$ ; (0, ) = max 1 (1), x 2 (1 ;  $\sum_{y=1}^{x} E_1$ 

The rest of the proof is devoted to establishing (2.10). Let us begin by recording for later use that

(2.11)   
\n
$$
\begin{array}{ccccccccc}\n\bullet & \text{max} & 1: (x) & 1 (0) & 1 & 0, \text{ as } 1 & 0, \\
\bullet & \text{max} & 1: (x) & 1 (1) & 1 & 0, \text{ as } 1 & 0\n\end{array}
$$

Fix a genericu 2 W<sup>1;1</sup> (; R<sup>N</sup>), x 2 [Q1] and  $Ox'' < 1=3$  and de ne

$$
A \cdot (x) := [x \quad "; x + "] \setminus [0 1]
$$

We claim that there exist an increasing modulus of continuity  $C(Q, 1)$  with  $! (0) = 0$  such that

(2.12) 
$$
E_1
$$
 u;  $A_*(x)$  ess sup.  $x$ ;  $u(x)$ ;  $Du(y)$  ! ("):  
\n<sub>y2A+(x)</sub>

Indeed for a.e.y  $2 A<sub>r</sub>(x)$  we have x

## References

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- [A4] G. Aronsson, On the partial di erential equation  $u_x^2$  $\frac{2}{x}$ u<sub>xx</sub>  $\frac{10}{x}$ Q