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A SubRiemannian Santalo Formula with

## A SUB-RIEMANNIAN SANTAL O FORMULA WITH APPLICATIONS TO ISOPERIMETRIC INEQUALITIES AND FIRST DIRICHLET EIGENVALUE OF HYPOELLIPTIC OPERATORS

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Abstract. Sub-Riemannian geometry is a generalization of Riemannian one, to include nonholonomic constraints. In this paper we prove a nonholonomic version of the classical Santab formula: a result in integral geometry that describes the intric-type inequalities for a compact domain M with piecewise C<sup>2</sup> boundary. Moreover, we prove a universal (i.e. curvature independent) lower bound for the rst Diric hlet eigenvalue 1(M) of the intrinsic sub-Laplacian,

in terms of the rank k of the distribution and the length L of the longest reduced sub-Riemannian geodesic contained in M. All our results are sharp for the sub-Riemannian structures on the hemispheres of the complex and quaternionic Hopf brations:

L<sup>2</sup>;

 $S^{1} \downarrow S^{2d+1} \downarrow^{p} CP^{d}; S^{3} \downarrow S^{4d+3} \downarrow^{p} HP^{d}; d 1;$ 

where the sub-Laplacian is the standard hypoelliptic opera tor of CR and quaternionic contact geometries, L = and k = 2 d or 4d, respectively.

## 1. Introduction and results

Let (M;g) be a compact Riemannian manifold with boundary @M Santab formula [19, 43] is a classical result in integral geometry that destables the Liouville measure of the unit tangent bundle UM in terms of the geodesic ow t : UM ! UM. Namely, for any measurable function F : UM ! R we have

(1)  $Z Z Z Z_{(v)}$   $F = F(t_{(v)}) dt g(v; n_q)_q(v) (q);$ 

where is the surface form on @Minduced by the inward pointing normal vector n,  $_q$  is the Riemannian spherical measure or  $U_qM$ ,  $U_q^+$  @Mis the set of inward pointing unit vectors at q 2 @Mand`(v) is the exit length of the geodesic with initial vector v. Finally,

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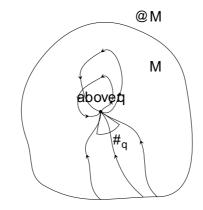


Figure 2. Visibility angle on a 2D Riemannian manifold. Only the geodesics with tangent vector in the dashed slice go t@M  $\,$ 

where  $diam_H$  denotes the horizontal diameter of the Carnot group.

In particular, if M is the metric ball of radius R, we obtain  $_1(M)$  k  $^2=(2R)^2$ . Clearly (9) is not sharp, as one can check easily in the Euclidean case

1.5. Isoperimetric-type inequalities. In this section we relate the sub-Riemannian area and perimeter of M with some of its geometric properties. Since M is compact, the sub-Riemann 10.9091 Tf 30.7199e

We can apply Proposition 7 to Carnot groups equipped with the Haar measure. In this case # = # = 1 and  $\hat{} = \text{diam}^{r}(M) = \text{diam}_{H}(M)$ . Moreover, ! is the Lebesgue volume of  $\mathbb{R}^{n}$  and is the associated perimeter measure of geometric measured by [16].

Corollary 9. Let M be a compactn-dimensional submanifold with piecewis  $\mathbb{C}^2$  boundary of a Carnot group of rank k, with the Haar volume. Then,

$$\frac{(@M)}{!(M)} \quad \frac{2 j S^{k-1} j}{j S^{k} j \operatorname{diam}_{H}(M)};$$

where diam<sub>H</sub> (M) is the horizontal diameter of the Carnot group.

This inequality is not sharp even in the Euclidean case, but **f** is very easy to compute the horizontal diameter for explicit domains. For example, if M is the sub-Riemannian metric ball of radius R, then diam<sub>H</sub> (M) = 2 R.

1.6. Remark on the change of volume. Fix a sub-Riemannian structure (N; D; g), a compact set M with piecewise C<sup>2</sup> boundary and a complementV such that (H1) holds. Now assume that, for some choice of volume form , also (H2) is satis ed, so that we can carry on with the reduction procedure and all our resultshold. One can derive the analogous of Propositions 2, 3, 4, 7 for any other volume  $^{0}$  = e<sup>'</sup> !, with ' 2 C<sup>1</sup> (M). In all these results, it is su cient to multiply the r.h.s. of the inequalities by the volumetric constant 0 < 1 de ned as :=  $\frac{\min e^{'}}{\max e^{'}}$ , and indeed replace! with !  $^{0}$  = e<sup>'</sup> ! in Propositions 2 and 3, with  $^{0}$  = e<sup>'</sup> in Proposition 7, and the sub-Laplacian ! with <sup>3</sup> !  $^{0}$ 

Furthermore, the

Remark 4. This construction gives a canonical way to de ne a measure or U M and its bers in the general sub-Riemannian case, depending only othe choice of the volume! on the manifold M. It turns out that this measure is also invariant under the Hamiltonian ow. Notice though that in the sub-Riemannian setting, ber s have in nite volume.

3.3. Invariance. Here we focus on the case of interest when E = T M is a rank k vector sub-bundle and  $E^0 = E$  is a corank 1 sub-bundle as de ned in Section 3.2. We stress **th**  $E^0$  is not necessarily a vector sub-bundle, but typically its bers are cylinders or spheres.

Recall that the sub-Riemannian geodesic ow  $_t$ : T M ! T M is the Hamiltonian ow of H : T M ! R. Moreover, in our picture, M N is a compact submanifold with boundary @Mof a larger manifold N, with dim M = dim N = n.

De nition 2. A sub-bundle E T M is invariant if  $_{t}()$  2 E for all 2 E and t such that  $_{t}()$  2 T M is de ned. A volume form 2  $^{n+k}(E)$  is invariant if  $L_{H} = 0$ .

Our de nition includes the case of interest for Santab formula, where sub-Riemannian geodesics may cros@M6; . In other words, E is invariant if the only way to escape from E through the Hamiltonian ow is by crossing the boundary 1(@M). Moreover, if is an invariant volume on an invariant sub-bundle E, then t = 0.

Lemma 12 (Invariant induced measures) Let E T M be a rank k

Writing XYu(x) = r(Yu)(x) X(x), where v w is the Euclidean scalar product of v; w 2 R<sup>n</sup>, proves the claim.

The above implies that the bracket [X; Y] is tangent to @Ma.e. on C(@M) for any X; Y 2 (D). In particular, this contradicts the bracket-generating assumption (11).

4.2. (Sub-)Riemannian Santal o formula. For any covector  $2 U_q M$ , the exit length `( ) is the rst time t 0 at which the corresponding geodesic (t) = t() leaves M crossing its boundary, while `( ) is the smallest between the exit and the cut length along (t). Namely

() = supft () j  $j_{[0;t]}$  is minimizingg:

We also introduce the following subsets of the unit cotangenbundle : U M ! M :

$$U^+ @M = f 2 U M j_{@M} jh; ni > 0g;$$

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Remark 5. Even if M is compact and hence < +1, in general  $\forall$  M (U M. Moreover, if also < +1 (that is, all geodesics reach the boundary of M in nite time), then U M = U M. Thus, our statement of Santab formula contains [19, Theorem VII.4.1].

Remark 6. If @Mis only Lipschitz and C(@M) has positive measure, the above Santab formulas still hold by removing on the left hand side from U M and U M the set f<sub>t</sub>() j () 2 C(@M) and t Og. Nothing changes on the right hand side as (C(@M)) = 0 by denition of n.

Proof. Let A [0; +1) U<sup>+</sup> @ M be the set of pairs (; ) such that 0 < t < `(). By Lemma 15 it follows that A is measurable. Let  $alsoZ = {}^{1}(@M)$  U M which clearly has zero measure irU M. De ne : A ! U M nZ as (t; ) = t(). This is a smooth di eomorphism, whose inverse is {}^{1}() = ( {}^{()}(); `()). In particular, U M is measurable. Then, using Lemma 17 (see below),

(17) 
$$\sum_{U \in M} F = \sum_{(A)} F = \sum_{A} (F) = \sum_{Z \in (C)} F = \sum_{A \in Z} (F) = \sum_{Z \in (C)} F(T_{A}) = \sum_{Q \in M} \sum_{U_{q}^{+} \otimes M} F(T_{Q}) = \sum_{Q \in M} F(T_{Q}$$

by Fubini Theorem. Analogously, with A = f(t; ) j 0 < t < `( )g and Z = Z [f () () j ) j = Z [f () () () j ]

 $2 U^+ @Mg$  the map : A ! U M nZ is a di eomorphism with the same inverse. Then, the same computations as (17) replacing A with A and Z with Z yield (16).

Lemma 17. The following local identity of elements of  $^{2n}$  (R U<sup>+</sup> @M) holds

₩/Tefe(i)in/.5d/h3m2a45360/clin3a6096(d),5.0FdT[(+)/5]TJ2.453(i)-1.3360688621(h)-5.4449R57 4d [(+)-1.69395]T.

$$=_{e};$$
  $=\frac{1}{!(x)}dp;$   $=_{n}!;$   $!=!(x)dx:$ 

Proof. For any (t; ) 2 R U<sup>+</sup> @ Mlet f @;  $v_1$ ; :::;  $v_{2n}$  2g be a set of independent vectors

Putting together (18), (19), and (20) completes the proof of the statement.

4.3. Reduced Santal o formula. The following reduction procedure replaces the noncompact set U M in Theorem 16 with a compact subset that we now describe.

To carry out this procedure we x a transverse sub-bundleV TM such that TM = D V. We assume thatV is the orthogonal complement of D w.r.t. to a Riemannian metric g such that  $g_{j_D}$  coincides with the sub-Riemannian one and the associated Rimannian volume coincides with! In the Riemannian case, where is trivial, this forces ! = ! R, the Riemannian volume. In the genuinely sub-Riemannian case there is no loss of generality since this assumption is satis ed for any choice of .

De nition 3. The reduced cotangent bundles the rank k vector bundle : T M<sup>r</sup> ! M of covectors that annihilate the vertical directions:

 $T M^{r} := f 2 T M j h; v i = 0$  for all v 2 V g:

The reduced unit cotangent bundle is U M  $^r$  := U M  $\setminus$  T M  $^r$ .

Observe that U M<sup>r</sup> is a corank 1 sub-bundle of T M<sup>r</sup>, whose bers are sphere  $S^{k-1}$ . If T M<sup>r</sup> is invariant in the sense of De nition 2, we can apply the construction of Section 3.3. The Liouville volume on T M induces a volume on T M<sup>r</sup> as follows.

Let  $X_1$ ;:::; $X_k$  and  $Z_1$ ;:::; $Z_n_k$  be local orthonormal frames forD and V, respectively. Let  $u_i() := h; X_i$  and  $v_i() := h; Z_j$  is smooth functions on T M. Thus

$$T M' = f 2 T M j v_1() = ::: = v_n k() = 0 g:$$

For all q 2 M where the elds are de ned,  $(u; v) : T_q M ! R^n$  are smooth coordinates on the ber and hence  $@_1; :::; @_k, @_1; :::; @_n _k$  are vectors on  $T(T_q M) T(T M)$  for all 2 <sup>1</sup>(q). In particular, the vector elds  $@_1; :::; @_{o \text{ formula.}}$ 

Lemma 18 (Explicit reduced vertical measure). Let q<sub>0</sub> 2 M and x a set of canonical coordinates (p; x) such that  $q_0$  has coordinates  $x_0$  and

 $\begin{array}{l} f \hspace{0.1cm} @_{k_1}; \ldots; @_{k_k} g_{q_0} \hspace{0.1cm} \text{is an orthonormal basis of } D_{q_0}, \\ f \hspace{0.1cm} @_{k_{k+1}} \hspace{0.1cm} ; \ldots; @_{k_n} g_{q_0} \hspace{0.1cm} \text{is an orthonormal basis of } V_{q_0}. \end{array}$ 

In these coordinates!  $j_{x_0} = dx j_{q_0}$ . Then  $r_{q_0}^r = vol_{R^k}$  and  $r_{q_0}^r = vol_{S^{k-1}}$ . In particular,

$$U_{q_0}M^r = jS^{k-1}j;$$
 8q0 2 M;

where  $jS^{k-1}j$  denotes the Lebesgue measure  $S^{k-1}$  and  $vol_{R^k}$ ,  $vol_{S^{k-1}}$  denote the Euclidean volume forms of  $R^k$  and  $S^{k-1}$ .

We now state the reduced Santab formulas. The setsU

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q reach the whole Euclidean planeq ?f z = 0 g (the left-translation of  $R^{2d} = R^{2d+1}$ ). At q = (x; z) this is the plane orthogonal to the vector  $\frac{1}{2}$ Jx; 1 w.r.t. the Euclidean metric. 5.2.

5.2.1. Riemannian submersions. A Riemannian submersion (M;g) ! (M;g) is triv-

The orthogonal complement D := V<sup>?</sup> with the restriction  $g_{j_D}$  of the round metric de ne the standard sub-Riemannian structure on the complex Hopf brations. In real coordinates, as subspaces  $dR^{2d+2}$ , the hemisphere and its boundary are

$$M = S_{+}^{2d+1} := \begin{pmatrix} X^{d} \\ i=0 \end{pmatrix} x_{i}^{2} + y_{i}^{2} = 1 \text{ j } x_{0} \quad 0 \quad ; \quad @M = \begin{pmatrix} X^{d} \\ i=0 \end{pmatrix} x_{i}^{2} + y_{i}^{2} = 1 \text{ j } x_{0} = 0 \quad :$$

A di erent set of coordinates we will use is the following

$$(\#; w_1; \dots; w_d)$$
 7!  $p \frac{e^{j\#}}{1 + jwj^2}; p \frac{w_1 e^{j\#}}{1 + jwj^2}; \dots; p \frac{w_d e^{j\#}}{1 + jwj^2}$ 

where # 2 (; ) and w = ( $w_1$ ;:::; $w_d$ ) 2 C<sup>d</sup>. In particular ( $w_1$ ;:::; $w_d$ ) are inohomgeneous coordinates for CP<sup>d</sup> given by  $w_j = z_j = z_0$  and # is the ber coordinate. The north pole corresponds to# = 0 and w = 0. The hemisphere is characterized by# 2 [ $\frac{1}{2}$ ; $\frac{1}{2}$ ] and its boundary by cos(#) = 0.

Example 4 (Quaternionic Hopf brations). Let H be the eld of quaternions. If q = x + iy + jz + kw, with x; y; z; w 2



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Consider the subsetD = U<sup>+</sup> @ M \ f ` < +1g . Let f (t) := f ( t( )). For 2 D we have f (0) = f (`( )) = 0 and the one-dimensional Poincae inequality (25) gives

(27) 
$$\begin{array}{c} Z_{()} \\ 0 \\ 0 \end{array} h_{t}(); r_{H} f i^{2} dt = \begin{array}{c} Z_{()} \\ 0 \\ 0 \end{array} f^{0}(t)^{2} dt \quad \frac{2}{2} \begin{array}{c} Z_{()} \\ 0 \\ 0 \end{array} f^{0}(t)^{2} dt \quad \frac{2}{2} \begin{array}{c} Z_{()} \\ 0 \\ 0 \end{array} f^{0}(t)^{2} dt : \end{array}$$

Indeed we can replace with L, which is t-invariant. Then

$$\frac{jS^{k-1}j}{k} \sum_{M}^{Z} jr_{H} f(q) j^{2}! (q) \sum_{QM}^{Z} q^{M}$$

Proof of Proposition 4. With L := sup  $_{2U M^{T}}L($  ), the Hardy inequality (4) can be further simpli ed into Z

$$\frac{1}{M}$$
 jr <sub>H</sub>f j<sup>2</sup>!  $\frac{k^2}{L^2} \frac{Z}{M}$  f<sup>2</sup>!:

By the min-max principle (13), whenever any f 2  $C_0^1$  (M) such that  $\frac{R}{M}$  f<sup>2</sup>! = 1, we have

$$_{1}(M) = \sum_{M}^{2} jr_{H} f j^{2}! = \frac{k^{2}}{L^{2}}:$$

Proof of Proposition 5. Fix a north pole  $q_0$  and the hemisphereM

De nition 7. The sub-Riemannian diameter and reduced diameter are: diam(M) := sup f d(x; y) j x; y 2 Denote @ = ( @,;:.:; @, k) and @ = ( @,;:.:; @k) and @ = ( @,;:.:; @k) and @ = ( @,;:.:; @k). Recall that  $^{r}(@;@;@) = ( @;@;@;@) = ( 1)^{k(n k)} ( @;@;@;@)$ . Then, using twice  $(L_{H})(w) = H( (w)) (L_{H}(w))$  for any `-form and `-uple w, we obtain

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