

A SHAPE CALCULUS BASED METHOD FOR A TRANSMISSION PROBLEM WITH RANDOM INTERFACE

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Abstract. The present work is devoted to approximation of the statistic cal moments of the unknown solution of a class of elliptic transmission problems in R³ with uncertainly located transmission interfaces. Within this model, the di usion coe cient has a jump discontinuity across the random transmission interface which models linear di u6.12487(n)2.80666(e)5.25645(a)633.88 -9.36016 Td TJ 219.6 0 Td [(i)-6.1264(c)5.25339(a)4.03117(l)-352.4(f)-7.23528(r)-7.5753(a)4.03117(n)

t, the simulation parameters are

nexact e.g. due to imperfect measurement based on a larget b nite number of system mplete or stochsatic. Finally, parameters of ch is itself only anapproximation of the actual

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In this article we develop a deterministic method for numerical solution for a class of transmission problems with randomly perturbed interfaces. The equation tobe solved is of the form

$$r$$
 (ru) = f in D;

where D is a random bounded domain inR^3 and $D_+ = R^3 n \overline{D}$ is its complement. The domains share a common random surface, and the coe cient function takes (in general) distinct constant values in D and D₊, respectively. The solution u is subject to jump conditions across. A precise description of the model problem is deferred until Section 2.3, where a probabilistic perturbation model for the surface (and thus D) will be rigorously introduced. Within this model, the

with the natural inner product satisfying $hv_1 v_k; w_1 w_k i_{X^{(k)}} = hv_1; w_1 i_X ::: hv_k; w_k i_X$. Definition 2.1. For a random eld v 2 L^k(;X), its k-order moment M^k[v] is an element of X^(k) de ned by

(2.4)
$$M^{k}[v] := \sum_{\substack{v \in V \\ k-times}}^{Z} \frac{v(!)}{|v|} dP(!):$$

In the case k = 1, the statistical moment M ${}^{1}[v]$ coincides with the mean value of v and is denoted by E[v]. If k 2, the statistical moment M ${}^{k}[v]$ is the k

$$E[] = x + E[(x;)]n^{0}(x); x 2^{0}:$$

Without loss of generality, we may assume that the random perturbation amplitude (x;!) is centered, i.e.,

(2.9) E[(x;)] = 0 8x 2 ⁰:

the mean random interface is represented by

s 2 R, the Sobolev space $H_{mix}^{s}(G^{k})$ is de ned to be the space of all distributions $v(y_{1}; :::; y_{k})$ with $y_{1}; :::; y_{k}$ 2 G satisfying

(2.18)
$$kvk_{H_{mix}^{s}(G^{k})} := hv; vi_{H_{mix}^{s}(G^{k})}^{1-2} < 1;$$
$$Hv; wi_{H_{mix}^{s}(G^{k})} := \begin{pmatrix} X & X & Y^{k} & I \\ (1 + i)^{2s} & b_{r}; m b_{r}; m \end{pmatrix}$$

with the Fourier coe cients

(2.19)
$$b_{r,m} := \sum_{x_1 \ge S}^{Z} \sum_{x_k \ge S} v(x_1); \dots; (x_k)) \sum_{i=1}^{Y^k} Y_{i;m_i}(x_i) d_{x_1} \dots d_{x_k}$$

Recalling de nition (2.3) we observe that $H^s_{mix}(G^k)$ is isometrically isomorphic to the tensor product spaceH ${}^s(G)^{(k)}$. These spaces will be identi ed in what follows. We also use the notatio $H^s_{mix}(K^k)$ for the tensor product $H^s(K)^{(k)}$ where K is a compact subset of \mathbb{R}^3 .

Sobolev spaces on bounded domains $i\mathbb{R}^3$ are de ned, as usual, as spaces of all distributions whose partial derivatives are square integrable. Proper treatmet of the transmission problem (2.11a){(2.11d) in unbounded domains in \mathbb{R}^3 requires a special care. Following [17], for an unbounded domain U \mathbb{R}^3 we introduce the space

(2.20)
$$H^{1}_{w}(U) := v 2 D^{0}(U) : kvk_{H^{1}_{w}(U)} = \sum_{U}^{Z} jr vj^{2} + \frac{jv(x)j^{2}}{1+jxj^{2}} dx^{2} < +1$$
 :

Speci cally, for a given partition Rm

3.1. Perturbation of deterministic interfaces. In this subsection we collect several properties of perturbed interfaces which are important for the subsequent analysis. Assume that the perturbation function is a xed deterministic function in $W^{1;1}$ (⁰), in particular is independent of !. Then is defined by

$$(3.1) \qquad \qquad := f x + (x) n^{0}(x) : x 2 {}^{0}g; > 0:$$

As already noticed in Section 2.2, is a closed Lipschitz manifold in \mathbb{R}^3 provided 0 $_0$ and $_0$ is su ciently small. In this case introduces a decomposition of \mathbb{R}^3 into the interior and exterior subdomains D and D₊, respectively.

Following [20], we de ne a mapping T : R^3 ! R^3 which transforms ⁰ into and D⁰ into D, respectively, by

(3.2)
$$T(x) := x + (x) r^{0}(x); x 2 R^{3};$$

where ~ and r^0 are any smoothness-preserving extensions of and n^0 into R^3 . We require in particular that ~ 2 W^{1;1} (R³). Without loss of generality we assume that the extension ~vanishes outside a su ciently large ball $B_R := f x 2 R^3 : jxj < R g$ containing for any 0 0. This implies that the perturbation mapping T (x) is an identity in the complement B_R^c

where $_1, _2, _3$ are defined by (3.9) and $_4 := 0$ for notational convenience later. In particular, for su ciently small > 0, there holds

$$(3.12) (; x) = 1 + {}_{1}(x) + {}^{2}_{2}(x) + {}^{3}_{3}(x) c > 0 8x 2 R^{3}$$

Consider from now on su ciently small > 0. It follows from (3.10) and (3.12) that the ij -entry of the matrix A(;x) I is

(3.13)
$$A_{ij}(;)_{ij} = (;)^{1} A_{ijn}^{X^4}_{n-1} A_{ijn}_{ij}$$

Hence, (3.11) yields

 $kA_{ij}(;)$ $_{ij}k_{L^{1}(R^{3})}!$ 0 as ! 0;

proving (3.6).

From (3.13), we have

(3.14)
$$\frac{A_{ij}(;)_{ij}}{m} = (;)^{1} \sum_{n=1}^{X^{4}} h_{ijn} \sum_{ij=n}^{n-1} h_{ijn} \sum_{ij=n}^{N} (;)^{1} \sum_{n=1}^{X^{4}} h_{ijn} \sum_{ij=n}^{n-1} h_{ijn} \sum_{ij=n}^{N} (;)^{1} \sum_{n=1}^{X^{4}} h_{ijn} \sum_{ij=n}^{N} (;)^{1} \sum_{ij=1}^{X^{4}} h_{ijn} \sum_{ij=1}^{N} h_$$

Taking the limit when goes to 0, noting that (;)! 1, we obtain

Using the change of variables = T (x) and noting (3.11), we have

kv T
$$k_{L^{2}(R^{3})}^{2} = \int_{R^{3}}^{L} jv(y)j^{2}$$
 (; (T) ¹(y)) ¹ dy C kv $k_{L^{2}(R^{3})}$:

Therefore,

(3.18)
$$\lim_{l \to 0} q \frac{1}{1+j j^2} (; x) = 1 (v T)_{L^2(R^3)} = 0:$$

Furthermore, (3.3) also gives

$$q - \frac{1}{1+j j^{2}} v T v = q - \frac{1}{1+j j^{2}} v T v = p - \frac{p}{1+R^{2}} kv T v = k_{L^{2}(B_{R})}$$

Note that $\lim_{v \to 0} kv = T = vk_{L^2(B_R)} = 0$ if v is continuous. By using a density argument we deduce that $\lim_{v \to 0} kv = T = vk_{L^2(B_R)} = 0$ for v 2 L²(B_R). Hence,

$$\lim_{i \to 0} \frac{q_{i}}{1+j_{i}} \frac{q_{i}}{v_{i}} v T v_{L^{2}(\mathbb{R}^{3})} = 0:$$

The above identity and (3.18) together with the triangle inequality give the required result.

Lemma 3.4. For any function v 2 $H^{1}(R^{3})$, there holds

$$\lim_{t \to 0} \frac{q}{1+j j^2} \frac{(;)(v T) v}{div vV} = 0:$$

Proof. Noting (3.3), Lemma 3.1, (3.17) and the triangle inequality, we obtain

Recall from (3.9) that $_1 = \text{div V}$. It follows from (3.12) that

$$\frac{(;) 1}{(v T)}(v T) \quad v \operatorname{div} V = (v T) + (v + 3)(v T):$$

Employing the density argument as in proof of Lemma 3.3, we obtain

$$\lim_{v \to 0} k_{1}(v - T - v)k_{L^{2}(B_{R})} = 0 \text{ and } \lim_{v \to 0} k_{(2 + 3)}(v - T)k_{L^{2}(B_{R})} = 0;$$

so that

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3.2. Material and shape derivatives. In this subsection, for notational convenience we use the notation D for D or D_+ , and $H^1(D_-)$ for $H^1(D_-)$ or $H^1_w(D_+)$.

Definition 3.5. For any su ciently small , let v be an element in $H^1(D)$ or $H^{1=2}()$. The material derivative of v , denoted by v, is de ned by

$$(3.20) \underline{v} := \lim_{t \to 0} \frac{v + T + v^0}{t};$$

if the limit exists in the corresponding spaceH $^1(D^0)$ or H $^{1=2}(^0)$. The shape derivative ofv is defined by

(3.21)
$$v^{0} = \begin{pmatrix} v & r & v^{0} & V & \text{if } v & 2 & H^{1}(D); \\ v & r & \circ v^{0} & V & \text{if } v & 2 & H^{1=2}(); \end{pmatrix}$$

where r o denotes the surface gradient.

Lemma 3.6. If

- (i) The material and shape derivatives of the product w are $vw^0 + v^0w$ and $v^0w^0 + v^0w^0$, respectively.
- (iii) If v = v for all 0, then $\underline{v} = r v^0 V = r v V$ and $v^0 = 0$. (iv) If (ii) The material and shape derivatives of the quotienty =w are $(\underline{v}w^0 \quad v^0\underline{w}) = (w^0)^2$ and $(v^0w^0)^2$

$$J_{1}(D_{i}) := \int_{D_{i}}^{Z_{i}} v \, dx; \, J_{2}(D_{i}) := v \, d; \text{ and } dJ_{i}(D_{i}) j_{i} = 0 := \lim_{t \to 0} \frac{J_{i}(D_{i}) - J_{i}(D^{0})}{t}; \, i = 1; 2;$$

then

$$dJ_1(D)j_{=0} = Z V^0 dx + V^0 V; n^0 dx$$

and

$$dJ_{2}(D_{i})j_{i=0} = \sum_{0}^{Z} v^{0}d_{i} + \sum_{0}^{Z} \frac{@\theta}{@n^{177};40} dv_{0}(p^{0}) v^{0} V; n^{0} d_{i}$$

Proof. Statements (i){(iii) can be obtained by using elementary calculations. Statement (iv) is proved in [20, pages 113, 116]

Lemma 3.9. The material and shape derivatives of the normal eldn are given by

$$n'$$
 $\underline{n} = n^0 = r \circ :$

) =

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Proof. nWe start by recalling that the materi4(a)-5.8887(t)-419(t)2.56084(h)2

noting from (3.8) that

$$\lim_{t \to 0} J_{T}^{>} = \lim_{t \to 0} J_{T} = I:$$

Since I = $J_T^{-1}(T_x) J_T(x)$ for all x 2 R³, we have $0 = \frac{d}{d} J_T^{-1} J_T - j_{=0}$, which together with the product rule and (3.8) yields

(3.24)
$$\frac{d}{d} J_T^{>} (T (x)) =_0 = (J_{T^0})^{>} \frac{d}{d} (J_T^{>}) =_0 (J_{T^0})^{-1} = \frac{d}{d} (J_T) =_0 = J_V^{>};$$

We also have, using the fact that $J_{T^{\,0}}^{\,\,>}\,\,n^{\,0}\,\,$ = 1,

Simple calculation reveals that

(3.26)
$$J_V^> = r (n^0)^>$$
 and $(J_V^> + J_V)n^0 = r + r ; n^0 n^0$:

Inserting (3.24){(3.26) into (3.23), we obtain

$$\underline{n} = J_{V}^{>} n^{0} + \frac{1}{2} (J_{V}^{>} + J_{V}) n^{0}; n^{0} n^{0} = r + r ; n^{0} n^{0} = r _{0} ;$$

nishing the proof of the lemma.

3.3. Shape derivative of solutions of transmission problem . In this subsection, we shall discuss the existence of material and shape derivatives of the solions of transmission problems on perturbed interfaces. Consider a deterministic problem with respet to the reference interface ⁰:

(3.27a)
$$4 u^0 = f \text{ in } D^0 [D^0_+;$$

(3.27b)
$$u^0 = 0 \text{ on } 0;$$

$$\frac{@ u}{@n} = 0 \quad \text{on} \quad {}^{0};$$

(3.27d)
$$u^{0}(x) = O(jxj^{-1})$$
 when $jxj!1$:

The perturbed problem corresponding to the perturbed interface is given by

(3.28a)
$$4 u = f \text{ in } D [D_+;$$

$$(3.28b)$$
 [u] = 0 on

(3.28c)
$$\frac{@u}{@n} = 0 \quad \text{on} \quad ;$$

(3.28d)
$$u(x) = O(jxj^{-1})$$
 when $jxj!1$;

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where (cf. (2.10))

$$(x) = \begin{pmatrix} & ; & x \ 2 \ D \\ & + ; & x \ 2 \ D_{+} \end{pmatrix}$$

Lemma 3.10. Suppose
$$2 L^{2}(R^{3}) \setminus W_{0}$$
 and $2 C^{1}(^{0})$, then
(3.29) $\lim_{u \to 0} u = T = u^{0} = 0$:

Here W denotes the dual areas
$$dV$$
 with respect to the l^2 inner pro-

Here, W_0 denotes the dual space dW_0 with respect to the L²-inner product. Proof. By multiplying both sides of (3.28a) with an arbitrary function v 2 C_0^1 (R³) and integrating over D [D₊, we obtain

(3.30)
$$\int_{\mathbb{R}^3}^{\mathbb{Z}} \int_{\mathbb{D}}^{\mathbb{Z}} du(x) v(x) dx + \int_{\mathbb{D}_+}^{\mathbb{Z}} 4u(x) v(x) dx = \int_{\mathbb{D}_+}^{\mathbb{Z}} \int_{\mathbb{D}_+}^{\mathbb{Z}} du(x) v(x) dx = \int_{\mathbb{D}_+}^{\mathbb{Z}} du(x) dx =$$

Applying Green's identity and noting (3.28c), we obtain Z

(3.31) (x) r u (x) r v(x) =
$$Hf; vi_{L^2(R^3)} = 8v 2 C_0^1 (R^3)$$

Since the space C_0^1 (R³) is dense in W (see [17, Remark 2.9.3]), there holds

(3.32)
$$(x) r u (x) r v (x) = hf; v i_{L^2(R^3)} 8v 2 W:$$

Choosing v = u gives

ju
$$j_W^2$$
 'h f; u $i_{L^2(R^3)}$ k f k_W ku k_W :

It follows from Lemma 2.2 that

$$(3.33) ku k_W . kf k_W 'k f k_{W_0}$$

On the other hand, using the change of variables = T (y) in (3.32), we have (noting that (T (y)) = (y)

(3.34)
$$(y)(r w(y))^{>} A(; y)r (u T)(y) dy = \int_{D_{+}^{0}[D^{0}]}^{D_{+}^{0}[D^{0}]} f(T(y)) w(y) (; y) dy;$$

for any w 2 W₀. We also obtain from problem (3.27a){(3.27d) $\overline{7}$

(3.35)
$$(y) (r w(y))^{>} r u^{0}(y) dy = \int_{D_{+}^{0}[D^{0}]}^{D^{0}} f(y) w(y) dy;$$

for any w 2 W_0 . Subtracting (3.35) from (3.34) we deduce Z

$$(y)r w(y)^{>} r (u T)(y) u^{0}$$

Subtracting (3.37) from (3.38) yields Z

$$(3.39) \qquad \begin{array}{rcl} (y) \ r \ (z \ (y) & z(y)) & r \ w(y) \ dy \\ Z \\ (y) \ r \ (u \ T \)(y) & \underline{A(; y) \ I} & r \ u^{0}(y) A^{0}(0; y) & r \ w(y) \ dy \\ (y) \ r \ (u \ T \)(y) & \underline{A(; y) \ I} & r \ u^{0}(y) A^{0}(0; y) & r \ w(y) \ dy \\ (y) \ r \ (y) \ f \ (y) & f \ (y) & div \ V(y) \ f \ (y) & w(y) \ dy \\ (y) \ f \ (y) \ f \ (y) & (y) \ dy \\ (y) \ f \ (y) \ f \ (y) & (y) \ dy \\ (y) \ f \ (y) \ f \ (y) \ (y) \ (y) \ (y) \ (y) \ dy \\ (y) \ f \ (y) \ (y)$$

The rst integral in the right hand side of (3.39) can be written as Z

$$I_{1}(w) = \begin{cases} z \\ z^{D_{+}^{0}[D^{0}]} \\ + \\ D_{+}^{0}[D^{0}] \end{cases} (y) r (u T)(y) \frac{A(;y) I}{D_{+}^{0}[D^{0}]} A^{0}(0;y) r w(y) dy$$

single u^{0} and u^{0} an

Di erentiating by both sides, applying Lemma 3.8 we have

and (3.55) follows. An analogous estimate holds for

$$M^{k}[u \quad E[u]] \quad {}^{k}M^{k}[u^{0}] = {}^{k}M^{k}[u^{0}+(h \quad E[h$$

These equalities together with (4.7) imply

(4.10)
$$u^{0}(x) = \begin{pmatrix} (\forall S & W)(u^{0})(x) =: E & (u^{0})(x); & x \ge D^{0} \\ (W & \forall S_{+})(u^{0}_{+})(x) =: E_{+}(u^{0}_{+})(x); & x \ge D^{0}_{+}; \end{pmatrix}$$

(

The randomness of the interface (!) which is given via the randomness of the vector eldV(; x; !) implies the randomness in the solutionu. From (4.10), we have

$$u^{0}(x;!) = \begin{pmatrix} (E (u^{0}(!)j_{0})(x); x 2 D^{0}; \\ E_{+}(u^{0}_{+}(!)j_{0})(x); x 2 D^{0}_{+}; \\ \end{pmatrix}$$

Tensorizing and integrating both sides of the above equation, we deuce

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(4.11)
$$\operatorname{Cov}[u^0](x_1; x_2) = \begin{pmatrix} (\mathsf{E}_{;x_1} & \mathsf{E}_{;x_2})\operatorname{Cor}[u^0 j \circ](x_1; x_2); & x_1; x_2 & 2 & D^0; \\ (\mathsf{E}_{+;x_1} & \mathsf{E}_{+;x_2})\operatorname{Cor}[u^0_+ j \circ](x_1; x_2); & x_1; x_2 & 2 & D^0_+; \end{pmatrix}$$

and in general

$$(4.12) M^{k}[u^{0}](x_{1}; :::; x_{k}) = \begin{pmatrix} (E_{;x_{1}} & E_{;x_{k}})M^{k}[u^{0}j_{0}](x_{1}; :::; x_{k}); & x_{1}; :::; x_{k} & 2 D^{0}; \\ E_{+;x_{k}})M^{k}[u^{0}j_{0}](x_{1}; :::; x_{k}); & x_{1}; :::; x_{k} & 2 D^{0}; \\ E_{+;x_{k}})M^{k}[u^{0}j_{0}](x_{1}; :::; x_{k}); & x_{1}; :::; x_{k} & 2 D^{0}; \\ \end{pmatrix}$$

Equation (4.11) suggests that the covariance of the solution D^0 in D^0 can be computed from the correlation function of the Dirichlet data $u^0 j \circ$ on the transmission interface.

The jump conditions in (4.1) gives

(4.13)
$$u^{0}(!) = u^{0}_{+}(!) + g_{D}(!)$$
 on ⁰;

and

(4.14)
$$\left(\underbrace{S}_{\{z \xrightarrow{+} S_{+}\}} u^{0}_{+}(!) = g_{N}(!) \quad (S)g_{D}(!) \text{ on } ^{0}: \right)$$

We note that for a xed !~2 , the right $\underline{bap}_{22}d_{0}$ ide $~g_{N}~(!~)$ ($~S~)g_{D}~(!~)~2~H^{-1=2}(^{-0})$. The solution $u^{0}_{+}~(!~)~$ of (4.14) belongs to H $^{1=2}(^{-0}(u_{1}))$

and H¹⁼²() -elliptic, i.e.

(4.18)
$$B(v; v) = C_2 kv k_{H^{1=2}(0)}^2 = 8v \ 2 \ H^{1=2}(0);$$

where the positive constants C_1 and C_2 are independent of v.

Proof. The boundedness of the bilinear form B is derived directly from the boundedness of 1 and K. To prove ellipticity we rst note that the hypersingular operator D is H $^{1=2}(^{0})$ -semi-elliptic for all closed interface 0 , i.e.,

(4.19)
$$hDv; vi_{L_2(0)} Cjvj_{H^{1=2}(0)} 8v 2 H^{1=2}(0);$$

see e.g. [21, Corollary 6.25]. The Cauchy datau(; $\frac{@u}{@h}$) on ⁰ satisfy 0 1 0 1 0 1

(4.20)
$$\begin{array}{c} \begin{array}{c} U \\ B \\ @ \underline{@} u \\ \hline @ \underline{@} u \end{array} \begin{array}{c} A \\ B \\ @ \underline{@} u \\ \hline @ \underline{@} u \end{array} \begin{array}{c} A \\ B \\ B \\ \hline D \\ \hline D \\ \hline 2 \\ I \\ \hline 2 \\ I \\ \hline \end{array} \begin{array}{c} H \\ B \\ @ \underline{@} u \\ \hline & A \\ \hline @ \underline{@} u \\ \hline & A \end{array} \begin{array}{c} H \\ B \\ @ \underline{@} u \\ \hline & A \\ \hline & B \\ \hline & B \\ \hline & B \\ \hline & D \\ \hline & 2 \\ I \\ \hline \end{array} \begin{array}{c} H \\ B \\ & B \\ \hline \hline & B \\ \hline & B \\ \hline & B \\ \hline & B \\ \hline \hline & B \\ \hline & B \\ \hline & B \\ \hline \hline & B \\ \hline \hline \hline & B \\ \hline \hline \hline &$$

Substituting (4.8) into the second equation of (4.20) gives

$$\frac{@u}{@n} = Du + (\frac{1}{2}I + K^{0})V^{-1}(\frac{1}{2}I + K)u \quad \text{on} \quad {}^{0}:$$

This equation and (4.8) yield

S = D +
$$(\frac{1}{2}I + K^{0})V^{-1}(\frac{1}{2}I + K)$$
:

Noting that K⁰ is the adjoint operator of K, we have

(4.21) hS v; vi = hDv; vi + V
$$(\frac{1}{2}I + K)v$$
; $(\frac{1}{2}I + K)v$ 8v 2 H $^{1=2}(^{0})$:

Similarly, the exterior Dirichlet-to-Neumann operator S₊ satis es

$$S_{+} = D (\frac{1}{2}I K^{0})V^{1}(\frac{1}{2}I K)$$

and

(4.22)
$$hS_{r}v; vi = hDv; vi V^{-1}(\frac{1}{2}I K)v; (\frac{1}{2}I K)v 8v 2 H^{1=2}(^{0}):$$

From (4.21), (4.22), (4.19) and noting the H¹⁼²-ellipticity of the inverse operator of V, we derive

h[S]v; vi = (+ +) hDv; vi + V
$$(\frac{1}{2}I + K)v; (\frac{1}{2}V + K)v; (\frac{1}{$$

implies

Lemma 4.2. The bilinear form B(;): $H_{mix}^{1=2}(\ ^{0} \ ^{0})$ $H_{mix}^{1=2}(\ ^{0} \ ^{0})$! R is bounded and $H_{mix}^{1=2}(\ ^{0} \ ^{0})$ -elliptic, i.e.,

(4.28)
$$B(v;w) = C_1 kv k_{H_{mix}^{1=2}(0)} (v, w) kw k_{H_{mix}^{1=2}(0)} (v, w);$$

and

(4.29)
$$C_2 kv k_{H_{mix}^{1=2}(0)}^{2} B(v;v)$$

for all v; w 2 $H_{mix}^{1=2}$ (⁰ ⁰). By Lemma 4.2 there exists a unique solution of (4.27).

5. Examples. In this section, we consider the transmission problem (2.11a){(2.1d) where the random interface (!) is given by

$$(!) = fx + (x;!)n(x) : x 2 Sg:$$

Here, the reference interface ⁰ is the unit sphere S. The perturbation parameter (x;!) = a(!), where a(!) is uniformly distributed in [1;1]. The mean value E[] = 0 and the covariance Cov[](x;y) = Cor[](x;y) = 1 = 3. The interface (!) is a sphere of radius R(!) = 1 + a(!).

5.1. Analytic example. Firstly, we choose the right hand sidef to be r'

$$f(x) = \begin{pmatrix} (4r_x^2 & 1)^2 & \text{if } 0 & r_x & 1=2; \\ 0 & \text{if } 1=2 & r_x; \end{pmatrix}$$

where $r_x = jxj$. Then solution of the transmission problem with respect to the random interface (!) can be analytically computed as follows:

(5.1)
$$u(x;!) = \bigotimes_{\substack{k=1\\ k \neq 1}}^{8} \frac{1}{105} \frac{2}{5} r_{x}^{4} + \frac{r_{x}^{2}}{6} \frac{3}{105} r_{x} \frac{23}{840} + \frac{1}{105} \frac{1}{105} \frac{1}{105} r_{x} \frac{1}{2};$$

(5.1)
$$u(x;!) = \bigotimes_{\substack{k=1\\ k \neq 1}}^{8} \frac{1}{105} \frac{1}{105} \frac{1}{105} + \frac{1}{105} \frac{1}{1$$

In particular, the exact solution u^0 of the transmission problem on the reference interface 0

V [0xi) = ≩(We then compute the covariance of the solutionu by elementary calculations, noting (5.1), to obtain

(5.4) $\operatorname{Cov}_{u}(x;y) = \frac{(\frac{1}{3} \frac{[]^{2}}{(105)})}{(105)}$

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