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State estimation using model order reduction for unstable systems

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T b  , a  a cc  a a  ca  , fl d fl .
F a  , d c a  ab  a , ca   a  fi d
b   b  a ,  a  a , a  . T fi d 
b   a a  a  a  a  b  a  b  c
d a ca   c  a  . U  a    d a  b a a -
a Ga  -N d d   d c  a 
 a  ab  . I  a  a d , d  
d a a  b  ba  d a c  d  d d 
d c d ,  ab   . T  a ca   ,

$a, \quad ca, \quad Da \, a \, a \quad a \quad c \quad a \quad fi \, d \quad b \quad a \, b$
 $c \quad b \quad b \quad a \quad da \, a \quad a \quad ca \quad d \quad . \, I$
 $a \quad c \quad -d \quad a \, a \, a \quad da \, a \, a \quad (4D-Va)$
 $a \quad b \quad d \, a \, a \quad a \quad a \quad a \quad b$

$$_x (x) = f(x)^T f(x); \tag{1}$$

$f(x) \quad c \quad d \quad a \quad ca \quad d \quad T \quad ,$
 $d \, b \, a \quad a \quad a \quad a \quad Ga \quad -N \quad d,$
 $a \quad a \quad c \quad 4D-Va \quad [1, 2]. \, W \quad a \quad d$
 $a \quad c \quad a \quad d \quad Jac \, b \, a \quad , \quad c \quad f(x) \, a \, d$
 $c \quad Jac \, b \, a \quad , \quad a \quad ca \quad d \quad c \quad , \quad d$
 $a \quad a \quad a \quad d \quad (TLM). \, S \quad fica \quad ca$
 $d \, c \quad d \quad a \quad d \quad a \, d \quad ab \, b \, a$
 $I \quad ab \quad TLM \, a \quad d \quad a \quad ca \quad d$
 $a \quad a \quad ab \quad a \, fi \quad a \quad T \quad a \quad c$
 $b \, ab \quad a \quad a \quad ab \quad d \, b \quad d$
 $A \, c \quad d \, a \quad ac \quad d \, c \quad c \quad b$
 $(1) \quad a \quad a \quad TLM \, b \, a \quad a \quad d \quad d \, a \quad a \, a$
 $W \quad ad \quad a \quad a \quad ac \, ca \quad c$

$$\mathcal{S} : \begin{cases} \delta x_{i+1} &= M \delta x_i; \\ d_i &= H \delta x_i; \end{cases} \quad (6)$$
$$T : \mathbb{C} \rightarrow \mathbb{R}^{p-m}; \quad (7)$$

$$z \mapsto T(z) := H(zI - M)^{-1} B_0^{\frac{1}{2}}: \quad (8)$$

$$\mathcal{S}: \begin{cases} \delta \hat{x}_{i+1} &= U^T M V \delta \hat{x}_i; \\ \hat{d}_i &= H V \delta \hat{x}_i; \end{cases} \quad (9)$$
$$\|T - \hat{T}\|_{h_{\infty, \alpha}} \leq 2(\sigma($$

$$T = \frac{1}{\alpha} H(zI - \frac{1}{\alpha} M)^{-1} B_0^{\frac{1}{2}};$$

$$T = \frac{1}{\alpha} H(zI - \frac{1}{\alpha} M)^{-1} B_0^{\frac{1}{2}};$$

$\begin{aligned} & \text{Ga-N} \quad c \, d \quad . \quad A^{\bullet} a^{\bullet} \quad d \quad c \quad d \quad a \\ & d \quad a \quad \text{Ead} \quad d \quad x-z \quad a \quad d \quad ba \quad c \quad c \\ & ab \quad , \quad c \quad d \quad a \quad c \, a \quad , \quad , \quad a \\ & d \quad d \quad . \end{aligned}$

4.1. $E \, e \, e \, a \, de \, g$
 $\begin{aligned} & T \quad d \quad a \quad a \quad 2D \, \text{Ead} \quad d \quad [7] \quad a \quad d \quad - \\ & c \, b \, d. \, T \quad ba \, c \, a \quad b \, a \, a \quad a \quad d \quad a \quad , \, z, \\ & a \, d \, a \, b \quad d \quad a \, b \quad da \quad , \, z = \pm \frac{1}{2}. \\ & F \quad [8] \quad a \quad d \quad a \quad a \quad c \quad a \\ & c \quad (\text{QGPV}) \quad . \quad T \quad a \quad a \quad b \quad ba \\ & b \quad a \, c \, , \, b = b(x; z; t), \quad b \quad da \quad , \, z = \pm \frac{1}{2}, \, a \quad t = 0. \, T \\ & d \quad ca \quad c \quad d \quad ba \quad c \quad a \quad c- \\ & , \quad = (x; z; t), \quad c \quad a \quad fi \quad . \end{aligned}$

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial z^2} = 0; \quad z \in [-\frac{1}{2}; \frac{1}{2}]; \, x \in [0; X]; \quad (13)$$

$b \quad da \quad c \quad d$

$$\frac{\partial}{\partial z} = b; \quad z = \pm \frac{1}{2}; \, x \in [0; X]; \quad (14)$$

$\begin{aligned} P \quad ba \quad ba \, c \, a \quad a \quad ad \, c \, d \quad a \, b \quad ba \, c \, a \quad fi \\ a \, d \, c \, b \, d \, b \quad -d \quad a \, \text{QG} \quad d \, a \, c \quad a : \end{aligned}$

$$\left(\frac{\partial}{\partial t} + z \frac{\partial}{\partial x} \right) b = \frac{\partial}{\partial x}; \quad z = \pm \frac{1}{2}; \, x \in [0; X]; \quad (15)$$

$\begin{aligned} T \quad a \, a \, b \quad da \quad c \, d \quad x-d \quad c \quad a \quad a \quad b \quad d \, c \\ c \quad a \, a \, a \quad , \, t, \, a \, d \quad , \, z, \, b(0; z; t) = b(X; z; t) \, a \, d \, (0; z; t) = \\ (X; z; t). \, A \quad [8] \quad d \quad a \quad x, \, z, \, a \, d \, t. \\ I \quad a \, d \quad , \quad \text{Ead} \quad d \, d \, c \quad d \quad 11 \\ ca \quad a \quad c \quad . \, T \quad a \, 20 \, d \quad a \\ 40 \, d \quad , \quad d \quad a \quad c \quad b. \, T \quad ad \, c \quad a \\ a \, d \, c \quad d \quad a \, a \quad ad \, c \quad c \quad . \, W \quad [8] \quad , \quad a \\ d \, a \, . \, T \quad b \, a \quad a \quad H \, c \quad c \quad a \quad b \, a \quad a \\ a \quad , \quad a \, b \quad a \, c \quad . \end{aligned}$

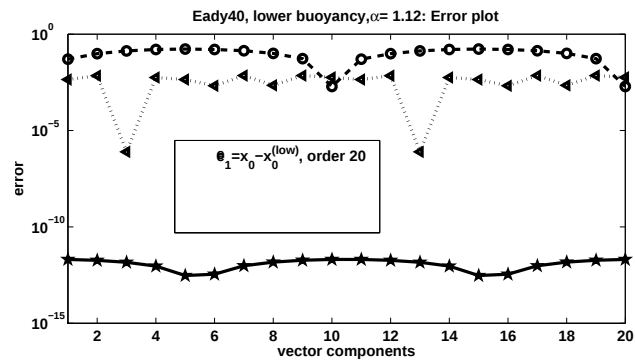
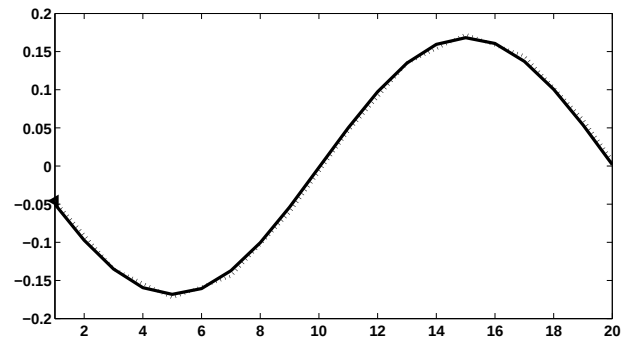
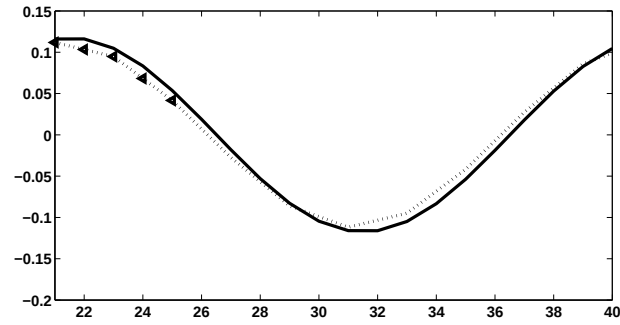


Figure 1: Comparison of low resolution (dotted line with triangles), standard balanced truncation (dashed line with circles), and the proposed method (solid line with squares). The proposed method shows the best performance in terms of accuracy and stability.

e

10 d , a d acc a .



(a) Solution on upper boundary

(b) Error on upper boundary

Figure 2: Comparison of low resolution (dotted line with triangles), standard balanced truncation (dashed line with circles) and α -bounded balanced truncation (solid line with stars) approximations to the buoyancy on the upper boundary

T a c T b fi ca b d a b a
c d c d d a W α -b d d
d b a c fica a
a ca d a d a da d
ba c d ca d F 3(a) a a
a a d (c) F 3(b), 4(a) a d
4(b) a d ff d a a T
 α -b d d a a d a c a a
, d a d c (F 3(b),

b a , a , a a a , a
 d . I 4D-Va d ac d b
 a a a b c a d b a d a
 a d c b a , a I
 a a a ca , c b d a
 a a Ga-N c d . Eac a d
 c a a a a b b c a d a
 a a d (TLM). T TLM d d c d, a a
 a d a b ab a fi d . T a c a
 d d a d, a a a d ab.
 U a TLM a a d b a d a a a
 I a a d a d d c d , α-
 b d d ba c d ca a b d b a b a a-
 ab TLM Ga-N c d . T d
 d c c c a d a a TLM
 ca c a I ca b a d d d
 b , ab , d c , a
 ba b d ca b d.
 T d d d c a a , a d
 d d d a , ab, a a , H ,
 b a d ac ca b
 K b ac c fi d c
 W a c a d α-b d d ba c d ca d
 a da d ba c d ca a ac , ab a d
 a a ca a 2-d a
 Ead d T Ead d a d , ba c c ab ,
 c d a c a , a d d
 I ca d a ca α-
 b d d a a d . I ca d a b a ,
 d d . T d a a b a c
 a d b da a d d ab , d d . I
 a d , a d b a a d
 a d a a a c

T a d a b NERC Na a C , Ea
 Ob a .

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